

and the second se	Main Fe	atures	6		
	Reference Product code Product refe Accessory m	rence		: CFW50 : 149783 : CFW50 : CFW50	0 G2
Basic data Power supply			: 380-480 V		
Input minimum-maximum v	oltage		: 323-528 V		
Number of phases			: 3		
- Input - Output			:3		
· .					
Supply voltage range					480 V
Overload cicle			Normal Overload (ND)		Heavy Overload (HD)
Rated current Overload current for 60 sec			Not applicable		24 A
Overload current for 3 sec			Not applicable Not applicable		36,0 A 48,0 A
Maximum applicable motor:					40,0 A
			Pow	er (HP/k	W) [1]
Voltage/Freque	ency		Normal Overload (ND)		Heavy Overload (HD)
380V / 50H:			Not applicable		15 / 11
380V / 60H:			Not applicable		15 / 11
400V / 50H:			Not applicable		15 / 11
400V / 60H			Not applicable		15 / 11
440V / 50H			Not applicable		15 / 11
440V / 60H			Not applicable		15 / 11
460V / 60H: 480V / 60H:			Not applicable		15 / 11 15 / 11
			Not applicable		15711
Accessory module (control)	I		: CFW500-IOS		
Dynamic braking [2]			: Standard with I	oraking	
External electronic suply 24	VCC		: Not available	- 44 4	
Safety Stop Internal RFI filter			: Prepared to us : Without filter	e the sat	ety module (G2)
External RFI filter			: Not available		
Link Inductor			: No		
Memory card			: Not included in	the proc	luct
USB port			: Only with plug-		
Line frequency			: 50/60Hz		
Line frequency range (mini	mum - maximum)		: 48-62 Hz		
Phase unbalance				o 3% of i	nput rated line voltage
Transient voltage and overv			: Category III		
Single-phase input current			: Not applicable		
Three-phase input current [ Typical input power factor	<u>]</u>		: 29,3 A : 0.75		
Displacement factor			: 0.98		
Rated efficiency			: ≥ 97%		
Maximum connections (pov	ver up cycles - on/	off) per ho	our : 10 (1 each 6 m	inutes)	
DC power supply	, , ,,	, i i i i	: Allow	,	
Standard switching frequen	су		: 5 kHz		
Selectable switching freque	ency		: 2.5 and 15 kHz	<u>-</u>	
Real-time clock			: Not available		
Copy Function			: Yes, by MMF o	r plug-in	or alphanumeric HMI
Dissipated power:					
Mounting type			Overloa	ad	
		N	ID		HD

405 W Surface 405 W Flange Not applicable Not applicable Source available to the user Output voltage : 24 Vcc Maximum capacity : 150 mA Control/performance data : Switched-mode power supply Power supply Control method - induction motor : V/f, VVW, Sensorless, Encoder and VVW PM Encoder interface : Only with plug-in : 0-500 Hz Control output frequency [5] The information contained are reference values. Subject 1/4 25/07/2025 to change without notice. Image merely illustrative.

Control/p	erformance	data
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Frequency resolution V/F Control - Speed regulation - Speed variation VVW Control - Speed regulation - Speed variation Sensorless vector control - Speed regulation - Speed variation Vector control with Encoder - Speed regulation - Speed variation **Analog Inputs** Quantity (standard) Levels Impedance for voltage input Impedance for current input Function Maximum allowed voltage **Digital inputs** Quantity (standard) Activation Maximum low level Minimum high level Input current . Maximum input current Function Maximum allowed voltage Analog outputs Quantity (standard) Levels RL for voltage output RL for current output Function **Digital outputs** Quantity (standard) Maximum voltage Maximum current Function Communication - Modbus-RTU (with accessory: Any plug-in module) - Modbus/TCP (with accessory CFW500-CEMB-

- TCP)
- Profibus DP (with accessory: CFW500-CPDP)
- Profibus DPV1 (with accessory: CFW500-CPDP)
- Profinet (with accessory CFW500-CEPN-IO)
- CANopen (with accessory: CFW500-CCAN)
- DeviceNet (with accessory: CFW500-CCAN)
- EtherNet/IP (with accessory CFW500-CETH-IP)
- EtherCAT (Not available)
- BACnet (CFW500 G2 / CFW501 G2 / MW500 G2
- with accessory: Any plug-in module)

## Available protection

- Output phase-phase overcurrente/Short
- Overcurrent/Short circuit phase-ground
- Under/Overvoltage in power
- Heat sink overtemperature
- Motor overload
- IGBT's modules overload
- Fault/External alarm
- Programming error

## **Operation interface (HMI)**

Avaliability

HMI installation Number of HMI buttons Display Indication accuracy

: 0,015 Hz

- : 1% of rated speed : 1:20
- : 1% of rated speed : 1:30
- : 0,5% of rated speed : 1:100
- : 0,1% of nominal speed : Up to 0 rpm

:1 : 0-10V, 0-20mA and 4-20mA : 100 kΩ : 500 Ω : Programmable : 30 Vcc

:4 : Active low and high : 5 V (low) e 15 V (high) : 9 V (low) e 20 V (high) : 4.5 mA : 5.5 mA : Programmable : 30 Vcc

: 1 : 0 to 10V, 0 to 20mA and 4 to 20mA : 10 kΩ : 500 Ω : Programmable

: 1 NO/NC relay and 1 transistor : 240 Vca and 24 Vcc : 0.5 A and 150 mA

: Programmable

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The information contained are reference values. Subject to change without notice. Image merely illustrative.

: Included in the product

: Fixed HMI

: Numeric LCD

: 5% of rated current

: 9





### **Operation interface (HMI)**

Ambient conditions	
Remote HMI degree of protection	: IP54
Remote HMI frame	: Not applicable
Remote HMI type	: Accessory
HMI battery life expectancy	: Not applicable
HMI battery type	: Not applicable
Standard HMI degree of protection	: IP66
Speed resolution	: 0,1 Hz

Enclosure Pollution degree : IP66 : 2 (EN50178 and UL508C)

Temperature around the inverter: of -10 °C / 14 °F to 40 °C / 104 °F. For temperatures above the specified is necessary to apply current reduction of 2 % per °C of 40 (104) to 50 °C (122 °F).

Relative humidity: 5% to 95% without condensation.

Altitude: up to 1000 m (3281 ft) under normal conditions. Of 1000 m (3281 ft) to 4000 m (13123 ft) reduce the current in 1% for each 100 m above (0,3% for each 100 ft above) of 1000 m (3281 ft). Reduce the maximum voltage (240 V for models 200...240 V, 480 V for models 380...480 V and 600 V for models 500...600 V) in 1,1% for each 100 m above (0,33% for each 100 ft above) of 2000 m.

### Sustainability policies

Dimensions and weigth	
Conformal Coating	: 3C2 (IEC 60721-3-3:2002)
RoHS	: Yes

## Dimensions and weigth

Differisions and weight	
- Size	: B (IP66)
- Height	: 340 mm / 13.4 in
- Width	: 215 mm / 8.46 in
- Depth	: 252.9 mm / 9.96 in
- Weight	: 9.3 kg / 20.5 lb
Mechanical Installation	
Mounting position	: Surface
Fixing screw	: M5
Tightening torque	: 5.5 N.m / 4.06 lb.ft
Allows side-by-side assembly	: No
Minimum spacing around the inverter:	
- Тор	: 50 mm / 1.97 in

Тор	: 50 mm / 1.97 in
Bottom	: 60 mm / 2.36 in
Front	: 50 mm / 1.97 in
Between inverters (IP20)	: 40 mm / 1.57 in

## **Electrical connections**

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Cable gauges and tightening torques:

	Recommended cable gauge	Recommended tightening torque
Power	6.0 mm² (10 AWG)	1.76 N.m / 1.30 lb.ft
Braking	6.0 mm² (10 AWG)	1.76 N.m / 1.30 lb.ft
Grounding	6.0 mm² (10 AWG)	0.5 N.m / 0.37 lb.ft
Control	0.5 to 1.5 mm <sup>2</sup> (20 to 14 AWG)	0,5 N.m / 0.37 lb.ft

SoftPLC	: Yes, incorporated
Maximum breaking current	: 34.0 A
Minimum resistance for the brake resistor	: 22 Ω
Recommended aR fuse [6]	: FNH00-63K-A
Recommended circuit breaker [6]	: MPW80i-3-U040
Disconnect switch	: With disconnect switch
Motor coupling box	: Not applicable
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## Standards

Otaniaanas			
Safety	<ul> <li>afety</li> <li>UL 508C - Power conversion equipment.</li> <li>UL 840 - Insulation coordination including clearances and creepage dis for electrical equipment.</li> <li>EN 61800-5-1 - Safety requirements electrical, thermal and energy.</li> <li>EN 50178 - Electronic equipment for use in power installations.</li> <li>EN 60204-1-Safety of machinery. Electrical equipment of machines. Pa 1: General requirements. Note: To have a machine in accordance with th standard, the manufacturer of the machine is responsible for the installat an emergency-stop device and a network switching equipment.</li> <li>EN 60146 (IEC 146) - Semiconductor converters.</li> <li>EN 61800-2 - Adjustable speed electrical power drive systems - Part 2: requirements - Rating specifications for low voltage adjustable frequency power drive systems.</li> </ul>		al and energy. tallations. t of machines. Part ccordance with that ble for the installation of uipment. systems - Part 2: General
Electromagnetic Compatibility         - EN 61800-3 - Adjustable speed electrical power drive systems - Part 3 product standard including specific test methods.           - EN 55011 - Limits and methods of measurement of radio disturbance characteristics of industrial, scientific and medical (ISM) radio-frequency equipment.		dio disturbance	
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Standards

Stanuarus	
	- CISPR 11 - Industrial, scientific and medical (ISM) radio-frequency equipment
	- Electromagnetic disturbance characteristics - Limits and methods of
	measurement.
	- EN 61000-4-2 - Electromagnetic compatibility (EMC) - Part 4: Testing and
	measurement techniques - Section 2: Electrostatic discharge immunity test.
	- EN 61000-4-3 - Electromagnetic compatibility (EMC) - Part 4: Testing
	and measurement techniques - Section 3: Radiated, radio-frequency,
	electromagnetic field immunity test.
	- EN 61000-4-4 - Electromagnetic compatibility (EMC) - Part 4: Testing and
	measurement techniques - Section 4: Electrical fast transient/burst immunity
	test.
	- EN 61000-4-5 - Electromagnetic compatibility (EMC) - Part 4: Testing and
	measurement techniques - Section 5: Surge immunity test.
	- EN 61000-4-6 - Electromagnetic compatibility (EMC)- Part 4: Testing and
	measurement techniques - Section 6: Immunity to conducted disturbances,
	induced by radio-frequency fields.
Mechanical Construction	- EN 60529 - degrees of protection provided by enclosures (IP code).
	- UL 50 - enclosures for electrical equipment.
	- IEC 60721-3-3 - classification of environmental conditions - part 3: classification
	of groups of environmental parameters and their severities - section 3: stationary
	use at weather protected locations level 3m4.

### Certifications

UL, CE, RCM, CS/IRAM, EAC, UKCA and RoHS CHINA

#### Notes

1) Motor power is orientative, valid for standard WEG Motors of IV poles. The correct sizing must be done according to the nominal current of the motor used, which must be less than or equal to the rated output current of the inverter;

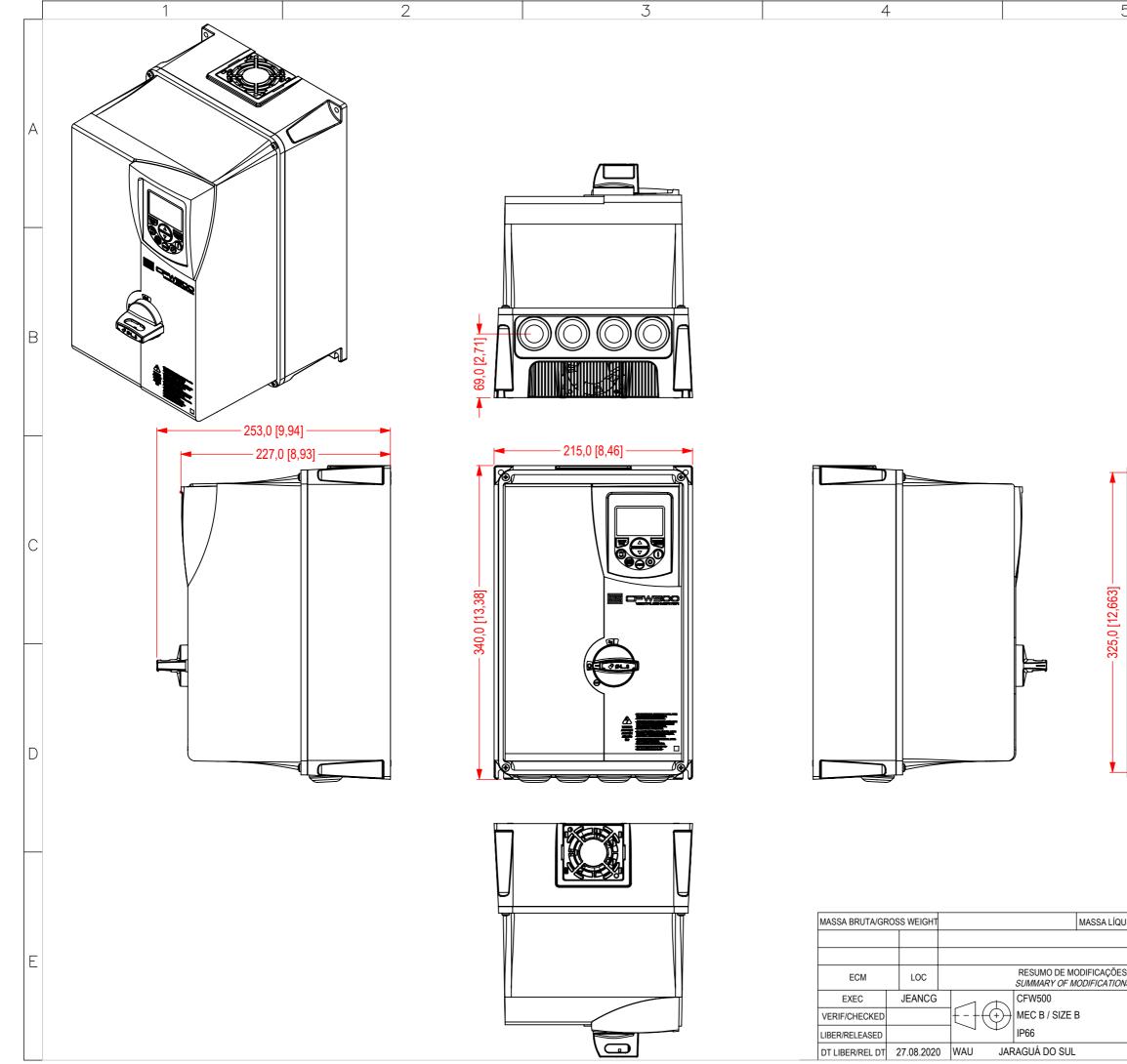
2) Braking resistor is not included;

3) Considering minimum line impedance of 1%;

4) For more information, refer to the user manual of CFW500 G2;

5) All images are merely illustrative.

6) For operation with switching frequency above nominal, apply derating to the output current (refer to the user manual).



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UIDA/NET WEIGHT			ESCALA/SCALE	3:1	
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